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Interference Reducing Networks

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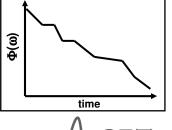
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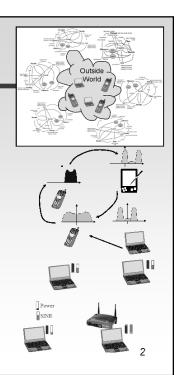
Problem Overview

Cognitive radios naturally interact Interaction can spawn infinite adaptations

Locally optimal decisions may be globally undesirable

Some localization required for scalable networks

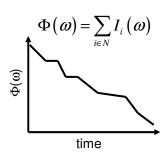
How to design cognitive radio networks that overcome these problems while using local reasoning?



Interference Reducing Networks

- Concept: Only permit adaptations which reduce the interference levels summed across all observations in the network
- Implies monotonic improvement in network performance – good convergence properties



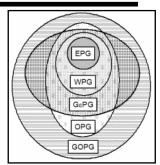


- Interference is a useful metric to minimize
 - Most networks are interference limited
 - Many other metrics monotonically improve with decreasing interference
 - Sum interference introduces symmetries exploitable for local reasoning

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Potential Game Model

 A potential game is a game where a single function – the potential function – captures every player's incentives when considering a unilateral adaptation



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Potential Game	Deviation Relationship ($\forall i \in N, \forall \in A$)
Exact (EPG)	$u_i(b_i, a_{-i}) - u_i(a_i, a_{-i}) = V(b_i, a_{-i}) - V(a_i, a_{-i})$
Weighted (WPG)	$u_i(b_i, a_{-i}) - u_i(a_i, a_{-i}) = \beta_i [V(b_i, a_{-i}) - V(a_i, a_{-i})]$
Ordinal (OPG)	$u_{i}\left(b_{i},a_{-i}\right)>u_{i}\left(a_{i},a_{-i}\right) \Leftrightarrow V\left(b_{i},a_{-i}\right)>V\left(a_{i},a_{-i}\right)$
Generalized Ordinal (GOPG)	$u_i(b_i, a_{-i}) > u_i(a_i, a_{-i}) \Rightarrow V(b_i, a_{-i}) > V(a_i, a_{-i})$
Generalized ε (GεPG)	$u_i(b_i, a_{-i}) > u_i(a_i, a_{-i}) + \varepsilon_1 \Longrightarrow V(b_i, a_{-i}) > V(a_i, a_{-i}) + \varepsilon_2$

Properties of Potential Games

- · Monotonicity
 - Potential function <u>monotonically increases</u> with every selfinterested unilateral adaptation
- Steady-state existence (compact space)
 - NE exist and can be identified by maximizers of potential function
- Convergence

	Timings			
	Round-			
Decision Rules	Robin	Random	Synchronous	Asynchronous
Best Response	1,2,4	1,2,4	-	1,2
Exhaustive Better Response	1,2	1,2	-	1,2
Random Better Response(s)	1,2,4	1,2,4	1,2	1,2
Random Better Response(b)	1,2	1,2	-	1,2
ε-Better Response ^(c)	1,2,3,4	1,2,3,4	-	1,2,3
Intelligently Random Better Response	1,4	1,4	-	1,2
Directional Better Response(c)	4	4	-	-
Averaged Best Response(d)	3,4	3,4	-	-
(a) Definition 4.12, (b) Definition 4.13, (c) Con-	vergence to	ın ε-NE, (d)	u, quasi-concave	in a _i
1.Finite game, 2. Infinite game with FIP, 3.		e with AFI	P, 4. Infinite ga	me with bounded
continuous potential function (implication of D)	P.			

- Optimality
 - Only optimal if potential function is a function you want maximized

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IRN and Potential Game

- Design potential game such that $V \propto -\Phi$
 - Self-interested adaptations will then monotonically increase V and decrease $\boldsymbol{\Phi}$

	Game	Utility Function Form	Potential Function
Altruism	Coordination Game	$u_i(a) = C(a)$	V(a) = C(a)
	Dummy Game	$u_{i}\left(a\right)=D_{i}\left(a_{-i}\right)$	$V(a) = c, c \in \mathbb{R}$
	Coordination-Dummy Game	$u_i(a) = C(a) + D_i(a_{-i})$	V(a) = C(a)
Isolated	Self-Motivated Game	$u_{i}\left(a\right)=S_{i}\left(a_{i}\right)$	$V\left(a\right) = \sum_{i \in N} S_i\left(a_i\right)$
Bilateral Symmetric Interference	Bilateral Symmetric Interaction (BSI) Game	$\begin{aligned} u_{i}\left(a\right) &= \sum_{j \in \mathcal{N}\left(k\right]} w_{ij}\left(a_{i}, a_{j}\right) - S_{i}\left(a_{i}\right) \\ \text{where } w_{ij}\left(a_{i}, a_{j}\right) &= w_{ji}\left(a_{j}, a_{i}\right) \end{aligned}$	$V\left(a\right) = \sum_{i \in N} \sum_{j=1}^{i-1} w_{ij}\left(a_{i}, a_{j}\right) - \sum_{i \in N} S_{i}\left(a_{i}\right)$
	Multilateral Symmetric Interaction (MSI) Game	$\begin{aligned} u_{i}\left(a\right) &= \sum_{\left\{S \in 2^{N}: s \in S\right\}} w_{S,i}\left(a_{S}\right) + D_{i}\left(a_{-i}\right) \\ \text{where } w_{S,i}\left(a_{S}\right) &= w_{S,j}\left(a_{S}\right) \forall i, j \in S \end{aligned}$	$V(a) = \sum_{S \in 2^{N}} w_{S}(a_{S})$
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Globally Altruistic Networks

Game	Utility Function Form	Deviation Relationship
Coordination Game	$u_i(a) = C(a)$	V(a) = C(a)

· Radio goal: minimize sum network interference

$$u_i(\omega) = -\Phi(\omega)$$

· Potential, Interference Function

$$V(\omega) = -\Phi(\omega)$$

- · Works for all waveform adaptations
- · Lots of overhead
 - Need to distribute observed interference levels to all decision processes
 - May be worse than a centralized solution

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Locally Altruistic Networks

Game	Utility Function Form	Deviation Relationship
Coordination Game	$u_i(a) = C(a)$	V(a) = C(a)

- Let $\mathcal{I}_i \subseteq N$ denote the set of radios which are close enough that i produces non-negligible interference.
- · Goal: minimize interference of those within "range"

$$u_{i}(\omega) = -\sum_{k \in \mathcal{I}_{i}} \sum_{j \in \mathcal{I}_{i} \setminus k} I_{i}(\omega)$$

- Same interference and potential function as before (just eliminated terms for which $I_i = 0$)
- Benefits
 - Less overhead, just as generalizable
 - Scales better
- Drawback Need extra routine to identify \mathcal{J}_i

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Isolated Adaptations

Game	Utility Function Form	Deviation Relationship
Self-Interested Game	$u_i(a) = S_i(a)$	$V(a) = \sum_{i \in N} S_i(a)$

- Concept: If an adaptation does not impact the performance of other radios then network is said to be an *isolated adaptation* network
- Radio goals: $u_i(\omega) = -I_i(\omega_i)$
- · Potential and Interference Function Relationship

$$V_i(\omega) = -\sum_{i \in N} I_i(\omega_i) = -\Phi(\omega)$$

- Successful implementation is very much dependent on the action sets
- · Limited (though non-trivial) set of allowable adaptations:
 - Receive beamforming
 - Internal settings (e.g., sampling rates, AGC gains. receive filters, MUD technique)
 - Error correction (assuming no raw data rate change)

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Bilateral Symmetric Interference

Game	Utility Function Form	Deviation Relationship
Bilateral Symmetric Interaction (BSI) Game	$\begin{aligned} u_i(a) &= \sum_{j \in \mathcal{N}(ij)} w_{ij}(a_i, a_j) - S_i(a_i) \\ \text{where } w_{ij}(a_i, a_j) &= w_{ji}(a_j, a_i) \end{aligned}$	$V(a) = \sum_{i \in \mathbb{N}} \sum_{j=1}^{i-1} w_{ij} \left(a_i, a_j \right) - \sum_{i \in \mathbb{N}} S_i \left(a_i \right)$

• Two cognitive radios, *j,k*∈ *N*, exhibit *bilateral symmetric interference* if

$$g_{jk}p_{j}\rho(\omega_{j},\omega_{k})=g_{kj}p_{k}\rho(\omega_{k},\omega_{j}) \ \forall \omega_{j} \in \Omega_{j}, \forall \omega_{k} \in \Omega_{k}$$

- ω_k waveform of radio k
- p_k the transmission power of radio k's waveform
- g_{kj} link gain from the transmission source of radio k's signal to the point where radio j measures its interference,
- $\rho(\omega_k, \omega_j)$ the fraction of radio K's signal that radio j cannot exclude via processing (perhaps via filtering, despreading, or MUD techniques).

Proof:

· By bilateral symmetric interference

$$g_{ki}p_{k}\rho(\omega_{k},\omega_{i})=g_{ik}p_{i}\rho(\omega_{i},\omega_{k})=b_{ik}(\omega_{i},\omega_{k})$$

Radio goal

$$u_{i}(\omega) = -I_{i}(\omega) = -\sum_{k \in N \setminus i} b_{ik}(\omega_{i}, \omega_{k})$$

• Therefore a BSI game $(S_i = 0)$ (an EPG)

$$V(\omega) = -\sum_{i=N} \sum_{k=1}^{i-1} g_{ki} p_k \rho(\omega_k, \omega_i)$$

• Interference Function

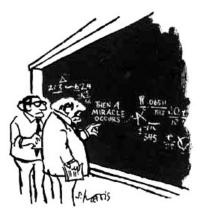
$$\Phi(\omega) = -2V(\omega)$$

• Therefore unilateral deviations increase V and decrease $\Phi(\omega)$ – an IRN

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Situations where BSI occurs



"I THINK YOU SHOULD BE MORE EXPLICIT HERE IN STEP TWO."

- $g_{jk}p_{j}\rho(\omega_{j},\omega_{k})=g_{kj}p_{k}\rho(\omega_{k},\omega_{j})$
- Isolated Network Clusters
 - All devices communicate with a common access node with identical received powers.
 - Clusters are isolated in signal space
- Close Proximity Networks
 - All devices are sufficiently close enough that waveform correlation effects dominate
- Controlled Observation Processes
 - Leverage knowledge of waveform protocol to control observations to achieve BSI

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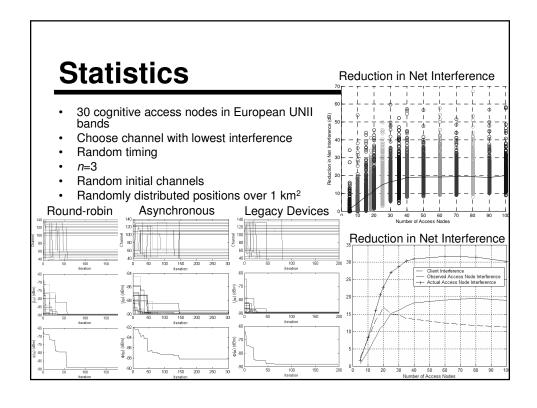
An IRN 802.11 DFS Algorithm Suppose each access node measures the received signal Listen on power and frequency of the Channel L RTS/CTS RTS/CTS (or BSSID) messages energy detected? Measure power sent by observable access of access node nodes in the network. in message, p Assumed out-of-channel interference is negligible and Note address of access RTS/CTS transmitted at same node, a Pick channel to Update $u_i(f) = -I_i(f) = -\sum_{k \in N \setminus i} g_{ki} p_k \sigma(f_i, f_k)$ interference table Time for decision? Apply decision $\sigma(f_i, f_k) = \begin{cases} 1 & f_i = f_k \\ 0 & f_i \neq f_k \end{cases}$ criteria for new

 $g_{jk} p_j \sigma(f_j, f_k) = g_{kj} p_k \sigma(f_k, f_j)$

operating channel, O

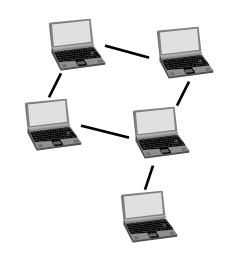
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Use 802.11h to signal change in O_C to clients



Problems Applying to Adhoc/P2P Network

- · No clear master node
- No clear reason to privilege one observation over others
- Link gain asymmetry violates BSI (previous trick required all observations to be made at transmitters)
- Could designate master devices (ala Bluetooth) and then run the same algorithm as the infrastructure algorithm



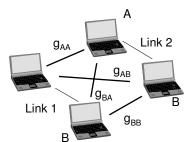
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Achieving BSI A Different Way

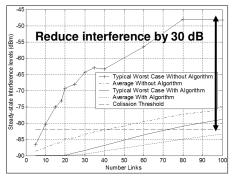
- Define players (decision processes) as links
 - Both sides of a link collaborate to make a decision
 - Permits incorporation of observations from both radios
- Consider Interference levels
 - Link 1
 - A $p(g_{AA} + g_{AB})\rho(f_1, f_2)$
 - B $p(g_{BA} + g_{BB})\rho(f_1, f_2)$
 - A+B $p(g_{AA} + g_{AB} + g_{BA} + g_{BB}) \rho(f_1, f_2)$
 - Link 2
 - A $p(g_{AA} + g_{BA})\rho(f_1, f_2)$
 - B $p(g_{AB} + g_{BB})\rho(f_1, f_2)$
 - A+B $p(g_{AA} + g_{AB} + g_{BA} + g_{BB})\rho(f_1, f_2)$

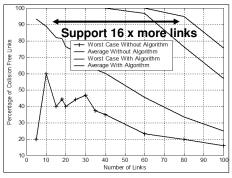
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Aggregate Statistics for P2P Network





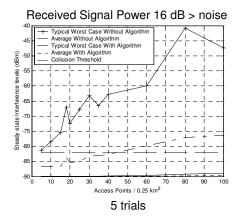
- · Similar algorithm but cognitive decision processes span links
- · No coordination between decision processes
- · Localized reasoning leads to global optima
- Steady-state performance equivalent to centralized local search

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More examples of synthesizing BSI

- Possible to create BSI where it does not naturally exist
 - Frequency + power
 - Activity rates
 - Transmit beamforming
 - Transmission times
- Come see my paper at the SDR Forum in November



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Summary

 Framework for designing local reasoning cognitive radio algorithms that lead to resource allocations that minimize interference

	Special	Waveform	Observation	Relative
Scenario	Topology	Restrictions	Restrictions	Overhead
Globally Altruistic	N	N	N	Very High
Locally Altruistic	N	N	N	High
Isolated Cluster	Y	Y	N	Low
Close Proximity	Y	Y	N	Low
Controlled Observation	N	Y	Y	Very Low

- BSI yields least overhead (no direct coordination between decision processes), but least applicable
- Techniques exist for synthesizing BSI conditions which still satisfy IRN framework

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Questions?







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